### TRADEMARK ASSIGNMENT COVER SHEET

Electronic Version v1.1 Stylesheet Version v1.2

ETAS ID: TM365076

SUBMISSION TYPE:	NEW ASSIGNMENT
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**NATURE OF CONVEYANCE:** ASSIGNMENT OF THE ENTIRE INTEREST AND THE GOODWILL

#### **CONVEYING PARTY DATA**

Name	Formerly	Execution Date	Entity Type
Seegrid Holding Corporation		01/26/2015	CORPORATION: DELAWARE

### **RECEIVING PARTY DATA**

Name:	Seegrid Corporation		
Street Address:	216 Parkwest Drive		
City:	Pittsburgh		
State/Country:	PENNSYLVANIA		
Postal Code:	15275		
Entity Type:	CORPORATION: DELAWARE		

### **PROPERTY NUMBERS Total: 10**

	1	1
Property Type	Number	Word Mark
Registration Number:	4060977	GUIDED BY SEEGRID
Registration Number:	4074853	GUIDED BY SEEGRID
Registration Number:	4088646	GUIDED BY SEEGRID
Registration Number:	3192951	
Registration Number:	4053971	SAFETYPICK
Registration Number:	3186929	SEEGRID
Registration Number:	3192993	SEEGRID
Registration Number:	4132666	THE MOST FLEXIBLE ORDER SELECTION ASSIST
Registration Number:	4136287	THE MOST FLEXIBLE SELECTION ASSISTANT
Registration Number:	3722759	WALKTHROUGHTHENWORK

### CORRESPONDENCE DATA

Fax Number: 4125621041

Correspondence will be sent to the e-mail address first; if that is unsuccessful, it will be sent

using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.

Phone: 412-562-1622

Email: vicki.cremonese@bipc.com

Duane A. Stewart III **Correspondent Name:** Address Line 1: 301 Grant Street

Address Line 2: 20th Floor

Address Line 4: Pittsburgh, PENNSYLVANIA 15219

ATTORNEY DOCKET NUMBER:	0085883-000001
NAME OF SUBMITTER:	Duane A. Stewart III
SIGNATURE:	/Duane A. Stewart III/
DATE SIGNED:	12/07/2015

### **Total Attachments: 21**

source=seegrid holding-seegrid corporation assignment#page1.tif source=seegrid holding-seegrid corporation assignment#page2.tif source=seegrid holding-seegrid corporation assignment#page3.tif source=seegrid holding-seegrid corporation assignment#page4.tif source=seegrid holding-seegrid corporation assignment#page5.tif source=seegrid holding-seegrid corporation assignment#page6.tif source=seegrid holding-seegrid corporation assignment#page7.tif source=seegrid holding-seegrid corporation assignment#page8.tif source=seegrid holding-seegrid corporation assignment#page9.tif source=seegrid holding-seegrid corporation assignment#page10.tif source=seegrid holding-seegrid corporation assignment#page11.tif source=seegrid holding-seegrid corporation assignment#page12.tif source=seegrid holding-seegrid corporation assignment#page13.tif source=seegrid holding-seegrid corporation assignment#page14.tif source=seegrid holding-seegrid corporation assignment#page15.tif source=seegrid holding-seegrid corporation assignment#page16.tif source=seegrid holding-seegrid corporation assignment#page17.tif source=seegrid holding-seegrid corporation assignment#page18.tif source=seegrid holding-seegrid corporation assignment#page19.tif source=seegrid holding-seegrid corporation assignment#page20.tif source=seegrid holding-seegrid corporation assignment#page21.tif

#### ASSIGNMENT

THIS ASSIGNMENT, by Seegrid Holding Corporation (formerly known as Seegrid Corporation), a corporation duly organized under and pursuant to the laws of Delaware and having its principal place of business at 216 Parkwest Drive, Pittsburgh, PA 15275 (hereinafter referred to as the "Assignor"), witnesseth:

WHEREAS, the Assignor is the owner of certain patents, patent applications, trademark registrations, trademark applications, copyrights, domain names, copyright applications, and trade secrets (collectively the "Intellectual Property") including but not limited to those properties set forth on **Exhibit A** hereto.

WHEREAS, Seegrid Corporation (formerly known as Seegrid Operating Corporation), a corporation duly organized under and pursuant to the laws of Delaware and having its principal place of business at 216 Parkwest Drive, Pittsburgh, PA 15275 (hereinafter referred to as the "Assignee"), is desirous of acquiring, and does hereby acquire, the entire right, title, and interest in and to the Intellectual Property, including but not limited to those properties set forth on **Exhibit A**.

NOW, THEREFORE, for good and sufficient consideration, the receipt of which is hereby acknowledged, and pursuant to the Contribution Agreement, dated January 26, 2015 by and between Assignor and Assignee, which was confirmed on January 20, 2015, by order of the United States Bankruptcy Court for the District of Delaware, the Assignor has sold, assigned, contributed, transferred, and set over, and by these presents does sell, assign, contribute, transfer, and set over, unto the Assignee, its successors, legal representatives, and assigns the entire right, title, and interest in and to the above-mentioned Intellectual Property, and all rights associated therewith, including the right of priority, the right to sue for present, past, and future infringement, and together with the goodwill of the business symbolized by the trademarks, as successor to the portion of the business to which the trademarks and trademark applications pertain, the Intellectual Property to be held and enjoyed by the Assignee, its successors, legal representatives, and assigns, as fully and entirely as the same would have been held and enjoyed by the Assignor had this assignment not been made;

AND for the same consideration, the Assignor hereby covenants and agrees to and with the Assignee, its successors, legal representatives, and assigns, that, at the time of execution and delivery of these presents, the Assignor is the sole and lawful owner of the entire right, title, and interest in and to the Intellectual Property, and that the Assignor has good and full right and lawful authority to sell and convey the same in the manner herein set forth;

AND for the same consideration, the Assignor, fully intending and expecting this Assignment to be effective for all of the Intellectual Property but recognizing that procurement and recordation of confirmatory assignments satisfactory to jurisdictions outside the United States may occur after the Effective Date of this Assignment, hereby grants to Assignee an exclusive, perpetual, royalty-free license in and to all of the Intellectual Property, with the

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expectation that the Assignee will continue to use any trademarks included in the Intellectual Property at the same level of quality with which they were used by the Assignor;

AND for the same consideration, the Assignor hereby covenants and agrees to and with the Assignee, its successors, legal representatives, and assigns, that the Assignor will, whenever counsel of the Assignee, or the counsel of its successors, legal representatives, and assigns, shall advise that any proceeding in connection with said Intellectual Property, or any reissue or extension thereof obtained or to be obtained thereon, is lawful and desirable, sign all papers and documents, take all lawful oaths, and do all acts necessary or required to be done for the procurement, maintenance, enforcement, and defense of the Intellectual Property, including execution of such further documents as may be necessary to record this transaction in the United States or any foreign jurisdiction, without charge to the Assignor, its successors, legal representatives, and assigns, but at the cost and expense of the Assignee, its successors, legal representatives, and assigns;

EFFECTIVE this 26th day of January, 2015 (the "Effective Date").

[SIGNATURES ON NEXT PAGE]

IN WITNESS WHEREOF, the Assignor has duly executed this Assignment, and the Assignee has accepted this Assignment, as of the date provided on the previous page.

# ASSIGNOR:

SEEGR	ID HOLDING CORPORATION	
Ву:	AMANI	_ (SEAL)
Name:	Jim Rocky	
Title:	/ CEO V	
ASSIG	NEE:	
SEEGR	ID CORPORATION	
	•	
Ву:	OAL	_(SEAL)
Name:	DAVID R. HEILMAN	·
Title:	PRESIDENT	

### EXHIBIT A

# Patents and Patent Applications

Country	Appln. Date	Appln. #	Grant Date	Patent #	Title
US	2/8/2006	11/350195	11/4/2008	7446766	MULTIDIMENSIONAL EVIDENCE GRIDS AND SYSTEM AND METHODS FOR APPLYING SAME
US	11/3/2008	12/263983	4/23/2013	8427472	MULTIDIMENSIONAL EVIDENCE GRIDS AND SYSTEM AND METHODS FOR APPLYING SAME
EP	2/8/2006	06734625.4			MULTIDIMENSIONAL EVIDENCE GRIDS AND SYSTEM AND METHODS FOR APPLYING SAME
KR	2/8/2006	10-2007-7020580	12/15/2010	10-1003168	MULTIDIMENSIONAL EVIDENCE GRIDS AND SYSTEM AND METHODS FOR APPLYING SAME
PCT	2/8/2006	PCT/US2006/004516			MULTIDIMENSIONAL EVIDENCE GRIDS AND SYSTEM AND METHODS
				·	FOR APPLYING SAME
US	2/8/2005	60/650904			THREE-DIMENSIONAL EVIDENCE GRIDS
US	6/11/2007	11/760859	2/1/2011	7880637	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
CA	6/11/2008	2690061	9/30/2014	2690061	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED

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					SIGNALS
DE	6/11/2008	602008020984.9	12/19/2012	2160929	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
EP	6/11/2008	08 770 632.1	12/19/2012	08 770 632.1	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
FR	6/11/2008	2160929	12/19/2012	2160929	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
GB	6/11/2008	2160929	12/19/2012	2160929	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
НК	6/11/2008	10 108 586.1	6/28/2013	HK1142214	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
PCT	6/11/2008	PCT/US2008/066473		11.5	LOW-PROFILE SIGNAL DEVICE AND METHOD FOR PROVIDING COLOR-CODED SIGNALS
US	1/28/2008	61/023980			METHOD FOR CLEANING UNDERNEATH FURNISHINGS FOR ROBOTIC CLEANER
US	1/28/2009	12/361300	11/18/2014	8892256	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS

					WITH ROBOTS THAT SERVICE A FACILITY
CN	1/28/2009	200980108309.X			METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
DE	1/28/2009	602009014163.5	3/20/2013	2249998	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
EP	1/28/2009	09 705 670.9	3/20/2013	2249998	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
FR	1/28/2009	2249998	3/20/2013	2249998	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
GB	1/28/2009	2249998	3/20/2013	2249998	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
НК	1/28/2009	11 104 801.8	7/5/2013	1150814	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
IT	1/28/2009	2249998	3/20/2013	2249998	METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
JP	1/28/2009	2010-545106	5/23/2014	5548139	METHODS FOR REAL- TIME AND NEAR-REAL

					TIME INTERACTIONS WITH ROBOTS THAT
					SERVICE A FACILITY
PCT	1/28/2009	PCT/US09/032243			METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
US	1/28/2008	61/024019			METHODS FOR REAL- TIME AND NEAR-REAL TIME INTERACTIONS WITH ROBOTS THAT SERVICE A FACILITY
US	1/28/2008	61/024001			METHODS FOR IMPROVING ROBOTIC CLEANING VIA GLOBAL LOCATION AWARENESS
US	1/28/2008	61/024022			METHODS AND APPARATUSES FOR NOISE REDUCTION FOR ROBOTIC VACUUMS
US	1/28/2008	61/024037	,		METHODS FOR ENVIRONMENTAL SCHEDULE AWARENESS FOR ROBOTS THAT SERVICE A FACILITY
US	1/28/2009	12/361441	9/16/2014	8838268	SERVICE ROBOT AND METHOD OF OPERATING SAME
DE	1/28/2009	602009007211.0	5/23/2012	2252190	SERVICE ROBOT AND METHOD OF OPERATING THE SAME
US	9/16/2014	14/487860			SERVICE ROBOT AND METHOD OF OPERATING SAME
EP	1/28/2009	09 706 723.5	5/23/2012	2252190	SERVICE ROBOT AND METHOD OF

					OPERATING THE SAME
FR	1/28/2009	09 706 723.5	5/23/2012	2252190	SERVICE ROBOT AND METHOD OF OPERATING THE SAME
GB	1/28/2009	09 706 723.5	5/23/2012	2252190	SERVICE ROBOT AND METHOD OF OPERATING THE SAME
HK	1/28/2009	11 104 794.7	9/28/2012	1150736	SERVICE ROBOT AND METHOD OF OPERATING THE SAME
PCT	1/28/2009	PCT/US2009/032274			SERVICE ROBOT AND METHOD OF OPERATING THE SAME
US	1/28/2008	61/024011			METHODS FOR OBJECT- AND SURFACE- SPECIFIC CLEANING FOR ROBOT CLEANERS
US	1/28/2009	12/361379	4/30/2013	8433442	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
CN	1/28/2009	200980108563.X			METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
DE	1/28/2009	602009014374.3	3/27/2013	2249999	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
EP	1/28/2009	09 706 350.7	3/27/2013	2249999	METHODS FOR REPURPOSING TEMPORAL-SPATIAL

					INFORMATION COLLECTED BY SERVICE ROBOTS
FR	1/28/2009	2249999	3/27/2013	2249999	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
GB	1/28/2009	2249999	3/27/2013	2249999	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
НК	1/28/2009	11 104 779.6	7/5/2013	1150813	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
IT	1/28/2009	2249999	3/27/2013	2249999	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
JP	1/28/2009	2010-545107	9/5/2014	5606927	METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
PCT	1/28/2009	PCT/US2009/032245			METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS

US	1/28/2008	61/024028			METHODS FOR REPURPOSING TEMPORAL-SPATIAL INFORMATION COLLECTED BY SERVICE ROBOTS
US	2/13/2009	12/371281	6/17/2014	8755936	DISTRIBUTED MULTI- ROBOT SYSTEM
CN	2/13/2009	200980105256.6			DISTRIBUTED MULTI- ROBOT SYSTEM
EP	2/13/2009	09 710 577.9			DISTRIBUTED MULTI- ROBOT SYSTEM
HK	2/13/2009	11 104 375.4			DISTRIBUTED MULTI- ROBOT SYSTEM
JP	2/13/2009	2010-546923	2/7/2014	5469097	DISTRIBUTED MULTI- ROBOT SYSTEM
PCT	2/13/2009	PCT/US2009/034081			DISTRIBUTED MULTI- ROBOT SYSTEM
US	2/13/2008	61/028320			ARCHITECTURE AND DESIGN OF A MULTI- ROBOT SYSTEM
US	8/17/2009	12/542279	5/1/2012	8169596	SYSTEM AND METHOD USING A MULTI-PLANE
					CURTAIN
CA	8/13/2010	2807721			SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
CN	2/16/2012	201080036411.6			SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
US	4/30/2012	13/460096			SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
DE	8/13/2010	2467280	11/5/2014	6020100200	SYSTEM AND METHOD USING A MULTI-PLANE

				29	CURTAIN
EP	8/13/2010	10810425.8	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
FI	8/13/2010	2467280	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
FR	8/13/2010	2467280	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
GB	8/13/2010	2467280	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
НК	8/13/2010	12113390.5			SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
IT	8/13/2010	2467280	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
KR	8/13/2010	10-2012-7006927	11/6/2013	10-1328484	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
PCT	8/13/2010	PCT/US2010/045451			SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
SE	8/13/2010	2467280	11/5/2014	2467280	SYSTEM AND METHOD USING A MULTI-PLANE CURTAIN
US	6/22/2012	13/530876	11/18/2014	8892241	ROBOT-ENABLED CASE PICKING
CA	6/22/2012	2836933			ROBOT-ENABLED CASE PICKING
CN					ROBOT-ENABLED CASE PICKING

US	11/17/2014	14/543241			ROBOT-ENABLED CASE PICKING
EP	6/22/2012	12740753.4			ROBOT-ENABLED CASE PICKING
PCT	6/22/2012	PCT/US12/43801			ROBOT-ENABLED CASE PICKING
US	6/24/2011	61/501026			ROBOT-ENABLED CASE PICKING
US	6/24/2011	13/168639	10/21/2014	8864164	TUGGER ATTACHMENT
CA	12/6/2011	2819708			TUGGER ATTACHMENT
EP	12/6/2011	11846146.6			TUGGER ATTACHMENT
HK	4/14/2014	14103562.6			TUGGER ATTACHMENT
JP	12/6/2011	2013-543244			TUGGER ATTACHMENT
PCT	12/6/2011	PCT/US11/063390			TUGGER ATTACHMENT
US	12/6/2010	61/420103			TUGGER ATTACHMENT
US	3/15/2013	13/836619			MULTI-HEAD CAMERA
US	7/26/2011	29/398127	4/16/2013	D680,142	MULTI-CAMERA HEAD
ECD	1/26/2012	001981242	4/5/2012	001981242-	MULTI-CAMERA HEAD
				000	
US	12/31/2012	13/731897			AUTO-NAVIGATING VEHICLE WITH FIELD- OF-VIEW ENHANCING SENSOR POSITIONING AND METHOD OF ACCOMPLISHING SAME
EP	12/31/2012	12821358.4			AUTO-NAVIGATING VEHICLE WITH FIELD- OF-VIEW ENHANCING SENSOR POSITIONING AND METHOD OF ACCOMPLISHING SAME

PCT	12/31/2012	PCT/US12/72317			AUTO-NAVIGATING VEHICLE WITH FIELD- OF-VIEW ENHANCING SENSOR POSITIONING AND METHOD OF ACCOMPLISHING SAME
US	12/30/2011	61/581863			ROBOTIC VEHICLE WITH OPERATOR FIELD OF VIEW ENHANCING SENSOR POSITIONING AND METHOD OF ACCOMPLISHING SAME
US	NOT FILED				ROBOT COLLISION AVOIDANCE
US	10/30/2013	29/471328			VEHICLE INTERFACE MODULE
EP	4/24/2014	002452458	6/17/2014	002452458- 0001	ELECTRICAL DISPLAY MODULES
US	NOT FILED				INTERSECTION CONTROLLER SYSTEM AND METHOD FOR USE WITH ROBOTIC VEHICLES
US	3/15/2013	61/792178			ROBOTIC VEHICLE MODIFICATIONS AND
					ASSOCIATED METHODS
US	3/13/2014	61/952447			ROBOTIC VEHICLE MODIFICATIONS AND ASSOCIATED METHODS
US	3/4/2014	14/196147			RANGING CAMERAS USING A COMMON SUBSTRATE
PCT	10/21/2014	PCT/US14/61576			RANGING CAMERAS USING A COMMON SUBSTRATE
US	10/22/2013	61/894229			RANGING AND RANGE- FINDING SYSTEMS AND

			METHODS
	•		
1			

EXHIBIT A

# Trademarks and Trademark Applications

Mark	Country	Filed	Appln. #	Reg.Date	Reg. #
SEEGRID	CN	3/16/11	9217514	3/21/2012	9217514
SEEGRID	EP	3/3/2011	009782228	7/14/2011	009782228
SEEGRID	JP	3/2/2011	2011-14817	8/5/2011	5430030
SEEGRID	KR	3/2/2011	40-2011- 0010413	6/11/2012	40- 0922842
SEEGRID	US	6/24/10	85/070,665	11/22/2011	4,060,977
Guided by SEEGRID	US	7/2/2010	85/076,837	12/20/2011	4,074,853
	US	7/2/2010	85/076,828	1/17/2012	4,088,646

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	US	2/2/2006	78/805,128	1/2/2007	3,192,951
Qbot	Qatar	9/3/2012	76612		
Qbot	US	5/25/2012	85/635,121		
SAFETYPICK	US	9/24/2010	85/137,704	11/8/2011	4,053,971
SEEGRID	US	2/7/2006	78/808,572	12/19/2006	3.186,929
	CN	3/16/2011	9217515	3/21/2012	9217515
SEEGRID	EP	3/3/2011	009784091	7/14/2011	009784091
SEEGRID	JP	3/2/2011	2011-14807	8/5/2011	5430029
SEEGRID	KR	3/2/2011	40-2011- 0010412	9/6/2012	40- 0933268
SEEGRID	US	2/7/2006	78/808,573	1/2/2007	3,192,993
THE MOST FLEXIBLE ORDER SELECTION ASSIST	US	10/13/2010	85/151,773	4/24/2012	4,132,666
THE MOST FLEXIBLE SELECTION ASSISTANT	US	9/24/2010	85/137,756	5/1/2012	4,136,287
WALKTHROUGHTHENWORK	US	11/29/2006	77/052,669	12/8/2009	3,722,759

### EXHIBIT A

## Domain Name

Domain Name	Expiration Date
BETTERWAYFORDISTRIBUTION.CO	8/9/2014
BETTERWAYFORDISTRIBUTION.COM	9/16/2014
BETTERWAYFORDISTRIBUTION.NET	9/16/2014
BETTERWAYFORMANUFACTURING.CO	8/9/2014
BETTERWAYFORMANUFACTURING.COM	9/16/2014
BETTERWAYFORMANUFACTURING.NET	9/16/2014
BETTERWAYFORMATERIALSMOVEMENT.CO	8/9/2014
BETTERWAYFORMATERIALSMOVEMENT.COM	9/16/2014
BETTERWAYFORMATERIALSMOVEMENT.NET	9/16/2014
BETTERWAYFOROPERATIONS.CO	8/9/2014
BETTERWAYFOROPERATIONS.COM	9/16/2014
BETTERWAYFOROPERATIONS.NET	9/16/2014
BETTERWAYFORPUTAWAY.CO	8/9/2014
BETTERWAYFORPUTAWAY.COM	9/16/2014
BETTERWAYFORPUTAWAY.NET	9/16/2014
CARTDRIVER.BIZ	2/25/2015
CARTDRIVER.CO	8/9/2014
CARTDRIVER.COM	2/26/2015
CARTDRIVER.INFO	2/26/2015
CARTDRIVER.NET	2/26/2015
CARTDRIVER.ORG	2/26/2015
GP8BETTERWAY.CO	8/9/2014

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GP8BETTERWAY.COM	9/16/2014
GP8BETTERWAY.NET	9/16/2014
GT3BETTERWAY.COM	9/16/2014
GT3BETTERWAY.NET	9/16/2014
GUIDEDBYSEEGRID.BIZ	6/3/2015
GUIDEDBYSEEGRID.CO	8/9/2015
GUIDEDBYSEEGRID.COM	6/4/2015
GUIDEDBYSEEGRID.INFO	6/4/2015
GUIDEDBYSEEGRID.NET	6/4/2015
GUIDEDBYSEEGRID.ORG	6/4/2015
GUIDEDBYSEEGRID.US	6/3/2015
PALLETDRIVER.CO	8/9/2014
PALLETDRIVER.COM	8/2/2015
PALLETDRIVER.INFO	2/17/2015
PALLETDRIVER.NET	8/2/2015
PALLETDRIVER.ORG	2/17/2015
PALLETDRIVER.US	2/16/2015
PEOPLEPROCESSESPROBOTS.CO	8/9/2014
PEOPLEPROCESSESPROBOTS.COM	9/16/2014
PEOPLEPROCESSESPROBOTS.NET	9/16/2014
PROCESSESROBOTSPEOPLE.CO	8/9/2014
PROCESSESROBOTSPEOPLE.COM	9/16/2014
PROCESSESROBOTSPEOPLE.NET	9/16/2014
RIDETHROUGHTHENWORK.COM	11/28/2014
RIDETHRUTHENWORK.COM	11/28/2014

ROBOBURGH.CO	8/9/2014
ROBOBURGH.COM	8/2/2014
ROBOBURGH.NET	8/10/2016
ROBOTSAREABETTERWAY.CO	8/9/2014
ROBOTSAREABETTERWAY.COM	9/16/2014
ROBOTSAREABETTERWAY.NET	9/16/2014
ROBOTSBETTERWAY.CO	8/9/2014
ROBOTSBETTERWAY.COM	9/16/2014
ROBOTSBETTERWAY.NET	9/16/2014
ROBOTSINTHEWAREHOUSE.CO	8/9/2014
ROBOTSINTHEWAREHOUSE.COM	9/16/2014
ROBOTSINTHEWAREHOUSE.NET	9/16/2014
ROBOTSPROCESSESPEOPLE.CO	8/9/2014
ROBOTSPROCESSESPEOPLE.COM	9/16/2014
ROBOTSPROCESSESPEOPLE.NET	9/16/2014
SEEGRID.BIZ	1/18/2016
SEEGRID.CO	8/9/2015
SEEGRID.COM	8/2/2019
SEEGRID.INFO	1/19/2016
SEEGRID.NET	8/2/2015
SEEGRID.ORG	1/19/2016
SEEGRID.US	1/18/2016
SEEGRIDBETTERWAY.CO	8/9/2014
SEEGRIDBETTERWAY.COM	9/16/2014
SEEGRIDBETTERWAY.NET	9/16/2014

SEEGRIDISABETTERWAY.CO	8/9/2014
SEEGRIDISABETTERWAY.COM	9/16/2014
SEEGRIDISABETTERWAY.NET	9/16/2014
SUPPLYCHAINROBOTICS.CO	8/9/2015
SUPPLYCHAINROBOTICS.COM	8/2/2015
SUPPLYCHAINROBOTICS.NET	8/2/2015
SUPPLYCHAINROBOTICS.ORG	8/2/2015
WALKTHROUGHTHENWORK.CO	8/9/2014
WALKTHROUGHTHENWORK.COM	8/2/2014
WALKTHROUGHTHENWORK.NET	8/2/2014
WALKTHRUTHENWORK.COM	11/28/2014
WORKPARTNER.BIZ	8/1/2014
WORKPARTNER.CO	8/9/2014
WORKPARTNER.NET	8/2/2014
WORKPARTNER.ORG	8/2/2014
WORKPARTNER.US	8/1/2014
WORKPARTNERTECHNOLOGY.BIZ	8/1/2014
WORKPARTNERTECHNOLOGY.CO	8/9/2014
WORKPARTNERTECHNOLOGY.COM	8/2/2014
WORKPARTNERTECHNOLOGY.INFO	8/2/2014
WORKPARTNERTECHNOLOGY.NET	8/2/2014
WORKPARTNERTECHNOLOGY.ORG	8/2/2014
WORKPARTNERTECHNOLOGY.US	8/1/2014

		Ct. t
Before me, a Notary Public in and the	for the said County and ed that he is the person v	state, personally appeared who executed the foregoing
Assignment on behalf of SEEGRID HOLDI free and voluntary act and deed.	NG CORPORATION an	d acknowledged it to be his
Witness my hand and notarial seal thi	is day of	, 20
(Notarial Seal)		
	Notary Pu	blic
State ofss:  County of		
		State personally anneared
Before me, a Notary Public in and who acknowledg Assignment on behalf of SEEGRID CORF voluntary act and deed.	ged that he is the person	who executed the foregoing